

# Balance Principle of Rigid Rotor

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# Unbalance

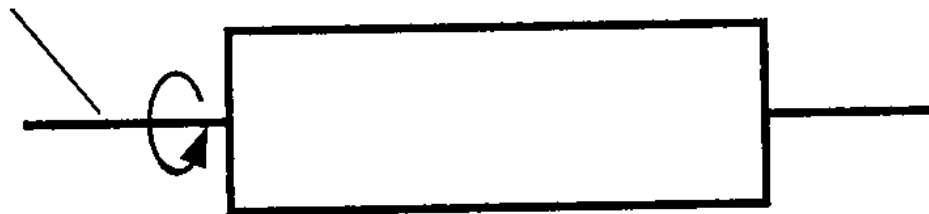
- Perfect Balance
- Rigid Rotor Unbalance
  - Static Unbalance
  - Dynamic Unbalance
- Flexible Rotor Unbalance
  - Critical Speed
  - Mode Shape

# Perfect Balance

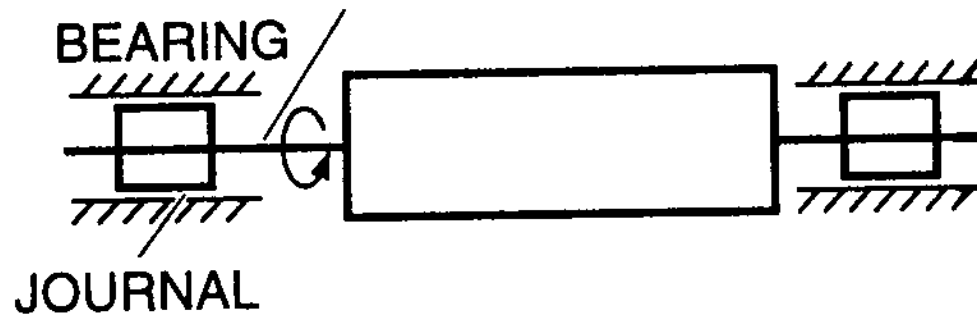
- A *rigid rotor* has a uniform speed of rotation about one of its three principal inertia axes.
- The *rigid rotor* rotates about the axis of rotation without wobbling; i.e., the principal axis coincides with a line fixed in space.

# Perfect Balance

PRINCIPAL AXIS



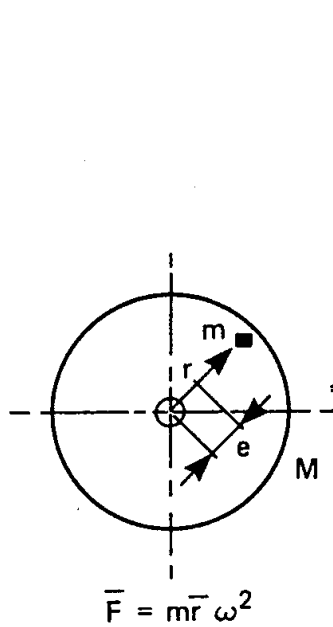
PRINCIPAL AXIS



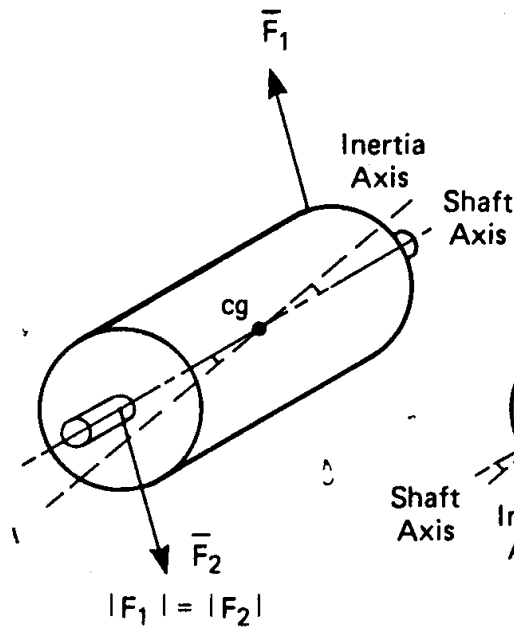
# Rigid Rotor Unbalance

- Static Unbalance (Static Balancing)
- Couple Unbalance (Two-Plane Balancing)
  - Static Balance + Nonzero moment about center of mass when rotates
  - Tilting of the principal inertia axis about the shaft axis at the center of mass
- Dynamic Unbalance (Two-Plane Balancing)
  - Static Unbalance + Couple Unbalance
  - The principal inertia axis inclined to the geometric shaft axis

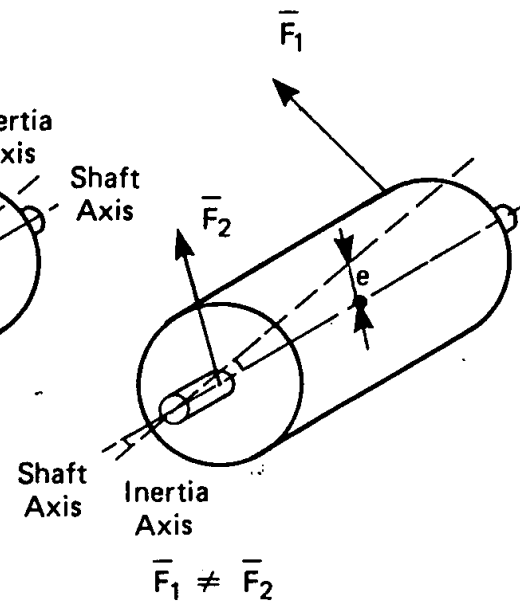
# Rigid Rotor Unbalance



(a) Static



(b) Couple



(c) Dynamic

# Rigid Rotor Unbalance

- Definition of Unbalance
  - $M$ : mass of a thin disc (unit:  $g$ )
  - $m$ : unbalance mass (unit:  $g$ )
  - $r$ : distance between the unbalance mass and axis of rotation (unit:  $mm$ )
  - $e$ : eccentricity, specific unbalance (unit:  $mm$ )
  - $F$ : centrifugal force (unit:  $\mu N$ )
  - $\omega$ : speed of rotation (unit:  $rad/sec$ )

# Rigid Rotor Unbalance

$$F = mr\omega^2$$
$$= Me\omega^2$$

- Unbalance ( $u$ ):

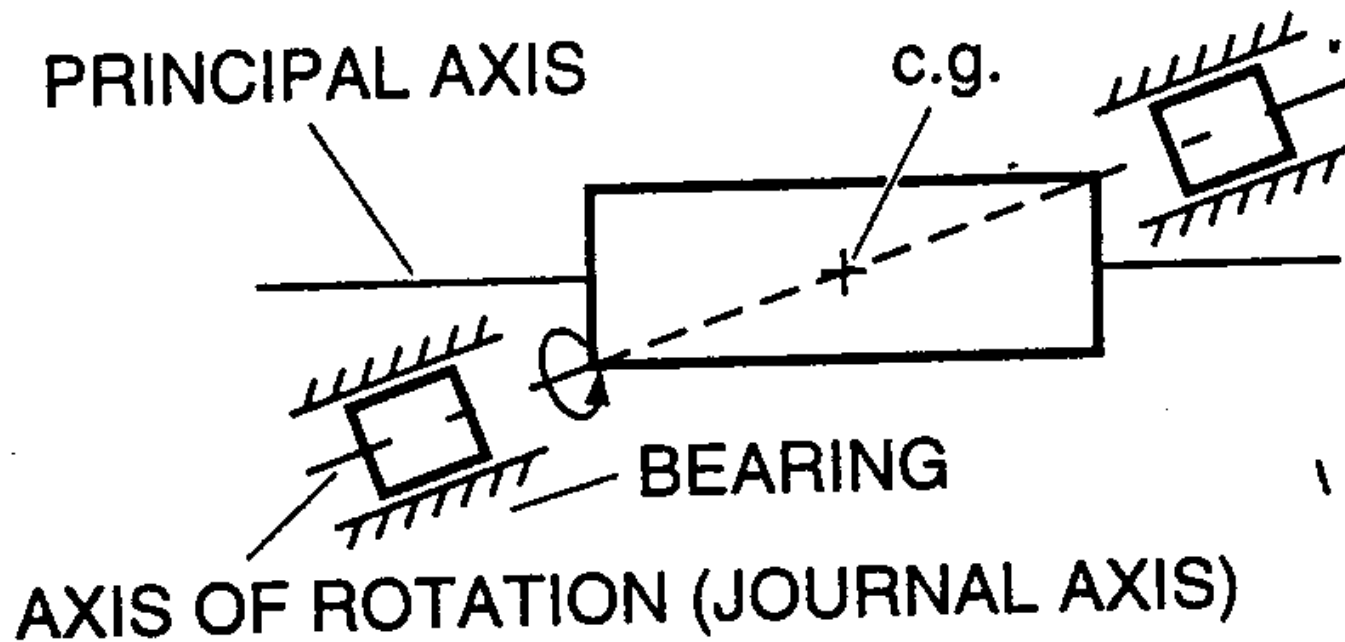
$$u = mr$$

- Specific Unbalance ( $e$ ):

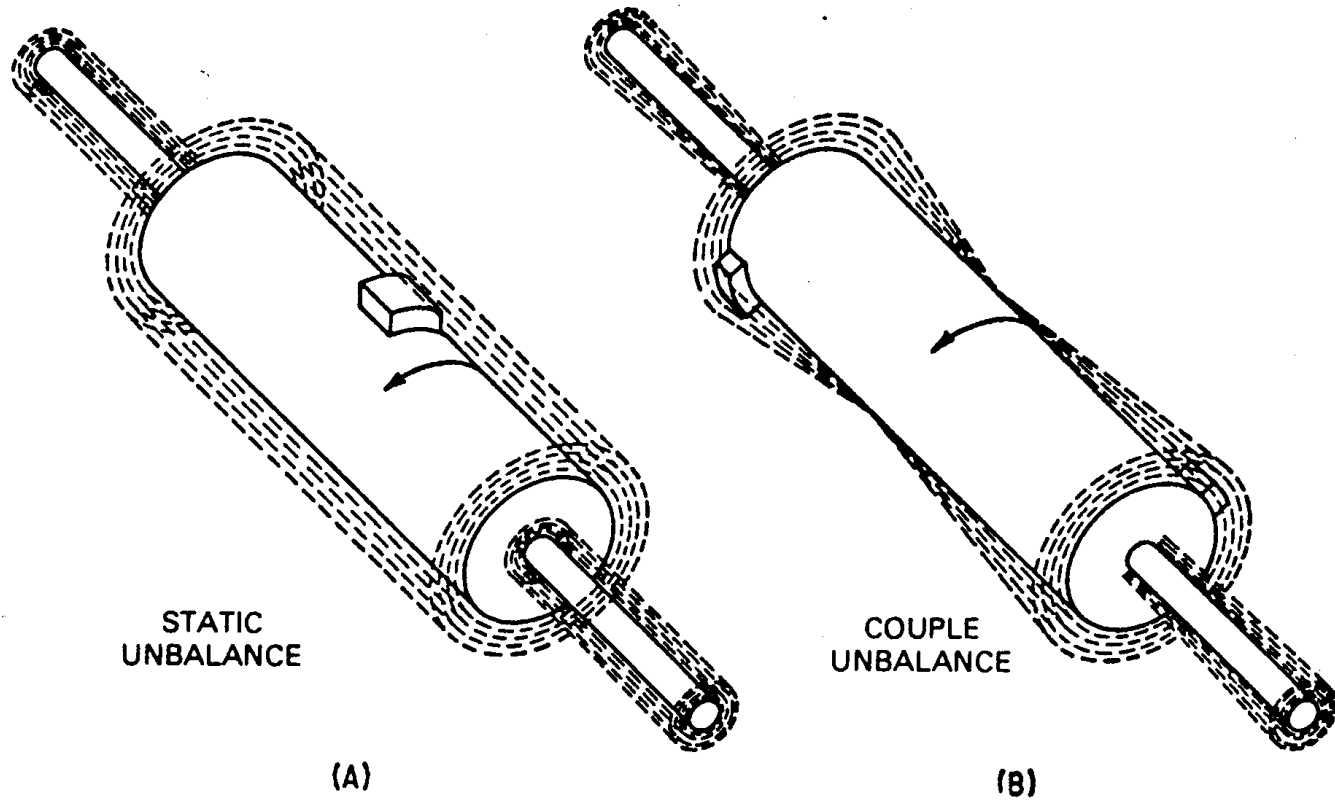
$$e = \frac{mr}{M}$$



# Rigid Rotor Unbalance



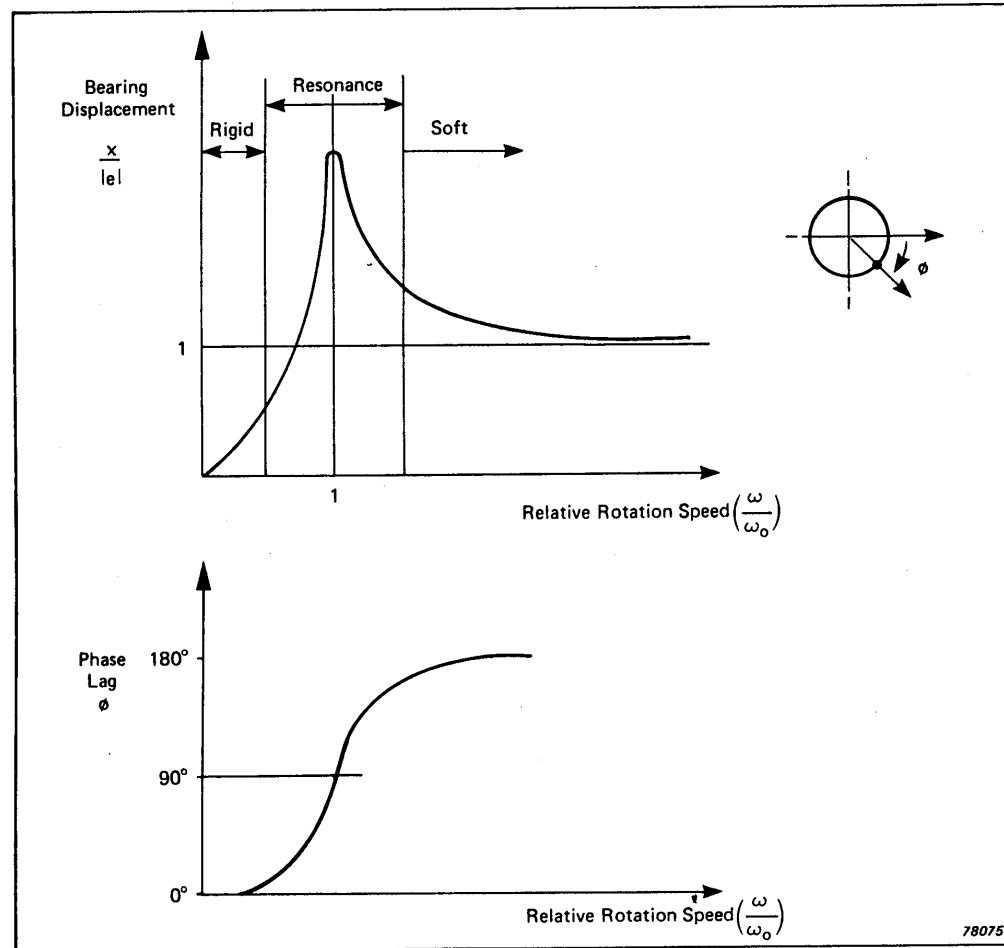
# Rigid Rotor Unbalance



**FIGURE 39.8** Effect of static and couple unbalance on free rotor motion.

# Rigid Rotor Unbalance

## Rigid Rotor and Bearing



# Rigid Rotor Unbalance

## Rigid Rotor and Bearing

